### INTEGRATED CIRCUITS

# DATA SHEET

For a complete data sheet, please also download:

- The IC06 74HC/HCT/HCU/HCMOS Logic Family Specifications
- The IC06 74HC/HCT/HCU/HCMOS Logic Package Information
- The IC06 74HC/HCT/HCU/HCMOS Logic Package Outlines

### **74HC/HCT221**

# Dual non-retriggerable monostable multivibrator with reset

Product specification Supersedes data of April 1988 File under Integrated Circuits, IC06 December 1990





### **74HC/HCT221**

#### **FEATURES**

- Pulse width variance is typically less than  $\pm 5\%$
- Pin-out identical to "123"
- · Overriding reset terminates output pulse
- nB inputs have hysteresis for improved noise immunity
- Output capability: standard (except for nR<sub>EXT</sub>/C<sub>EXT</sub>)
- I<sub>CC</sub> category: MSI

#### **GENERAL DESCRIPTION**

The 74HC/HCT221 are high-speed Si-gate CMOS devices and are pin compatible with low power Schottky TTL (LSTTL). They are specified in compliance with JEDEC standard no. 7A.

The 74HC/HCT221 are dual non-retriggerable monostable multivibrators. Each multivibrator features an active LOW-going edge input ( $n\overline{A}$ ) and an active HIGH-going edge input (nB), either of which can be used as an enable input.

Pulse triggering occurs at a particular voltage level and is not directly related to the transition time of the input pulse. Schmitt-trigger input circuitry for the nB inputs allow jitter-free triggering from inputs with slow transition rates, providing the circuit with excellent noise immunity.

Once triggered, the outputs  $(nQ, n\overline{Q})$  are independent of further transitions of  $n\overline{A}$  and nB inputs and are a function of the timing components. The output pulses can be terminated by the overriding active LOW reset inputs  $(n\overline{R}_D)$ . Input pulses may be of any duration relative to the output pulse.

Pulse width stability is achieved through internal compensation and is virtually independent of  $V_{CC}$  and temperature. In most applications pulse stability will only be limited by the accuracy of the external timing components.

The output pulse width is defined by the following relationship:

$$t_W = C_{EXT}R_{EXT}In_2$$
  
$$t_W = 0.7C_{EXT}R_{EXT}$$

Pin assignments for the "221" are identical to those of the "123" so that the "221" can be substituted for those products in systems not using the retrigger by merely changing the value of  $R_{\text{EXT}}$  and/or  $C_{\text{EXT}}$ .

#### **QUICK REFERENCE DATA**

 $GND = 0 V; T_{amb} = 25 °C; t_r = t_f = 6 ns$ 

SYMBOL	PARAMETER	CONDITIONS	TYP	UNIT	
STIVIBUL	PARAIVIETER	CONDITIONS	нс	нст	UNII
	propagation delay	C <sub>L</sub> = 15 pF; V <sub>CC</sub> = 5 V;			
t <sub>PHL</sub>	$n\overline{A}$ , $nB$ , $n\overline{R}_D$ to $nQ$ , $n\overline{Q}$	$R_{EXT} = 5 \text{ k}\Omega; C_{EXT} = 0 \text{ pF}$	29	32	ns
t <sub>PLH</sub>	$n\overline{A}$ , $nB$ , $n\overline{R}_D$ to $nQ$ , $n\overline{Q}$		35	36	ns
C <sub>I</sub>	input capacitance		3.5	3.5	pF
C <sub>PD</sub>	power dissipation capacitance per package	notes 1 and 2	90	96	pF

#### Notes

1.  $C_{PD}$  is used to determine the dynamic power dissipation ( $P_D$  in  $\mu W$ ):

$$P_D = C_{PD} \times V_{CC}^2 \times f_i + \sum (C_L \times V_{CC}^2 \times f_o) + 0.33 \times C_{EXT} \times V_{CC}^2 \times f_o + D \times 28 \times V_{CC} \text{ where:}$$

f<sub>i</sub> = input frequency in MHz; f<sub>o</sub> = output frequency in MHz

$$\sum (C_L \times V_{CC}^2 \times f_0) = \text{sum of outputs}$$

C<sub>EXT</sub> = timing capacitance in pF; C<sub>L</sub> = output load capacitance in pF

V<sub>CC</sub> = supply voltage in V; D = duty factor in %

2. For HC the condition is  $V_I = GND$  to  $V_{CC}$ 

For HCT the condition is  $V_I$  = GND to  $V_{CC}$  – 1.5 V

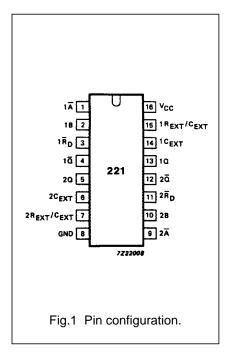
### 74HC/HCT221

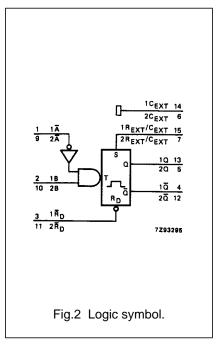
#### **ORDERING INFORMATION**

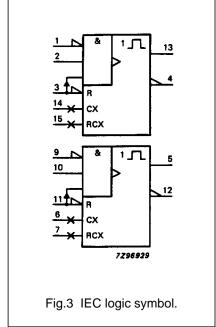
See "74HC/HCT/HCU/HCMOS Logic Package Information".

#### **PIN DESCRIPTION**

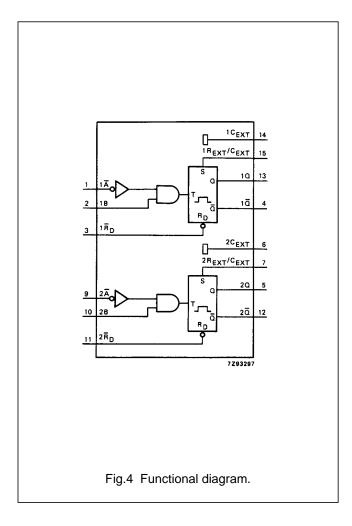
PIN NO.	SYMBOL	NAME AND FUNCTION
1, 9	1 <del>A</del> , 2 <del>A</del>	trigger inputs (negative-edge triggered)
2, 10	1B, 2B	trigger inputs (positive-edge triggered)
3, 11	$1\overline{R}_D$ , $2\overline{R}_D$	direct reset inputs (active LOW)
4, 12	1\overline{Q}, 2\overline{Q}	outputs (active LOW)
7	2R <sub>EXT</sub> /C <sub>EXT</sub>	external resistor/capacitor connection
8	GND	ground (0 V)
13, 5	1Q, 2Q	outputs (active HIGH)
14, 6	1C <sub>EXT</sub> , 2C <sub>EXT</sub>	external capacitor connection
15	1R <sub>EXT</sub> /C <sub>EXT</sub>	external resistor/capacitor connection
16	V <sub>CC</sub>	positive supply voltage







### 74HC/HCT221



#### **FUNCTION TABLE**

	INPUTS	OUTPUTS					
$n\overline{R}_D$	nĀ	nB	nQ	nQ			
L	Х	Х	L	Н			
Х	Н	X	L <sup>(2)</sup>	H <sup>(2)</sup>			
Х	X	L	L (2)	H <sup>(2)</sup>			
Н	L	<b>1</b>	工				
Н	$\downarrow$	Н	工				
<b>↑</b>	L	Н	(3)	(3)			

#### **Notes**

1. H = HIGH voltage level

L = LOW voltage level

X = don't care

↑ = LOW-to-HIGH level

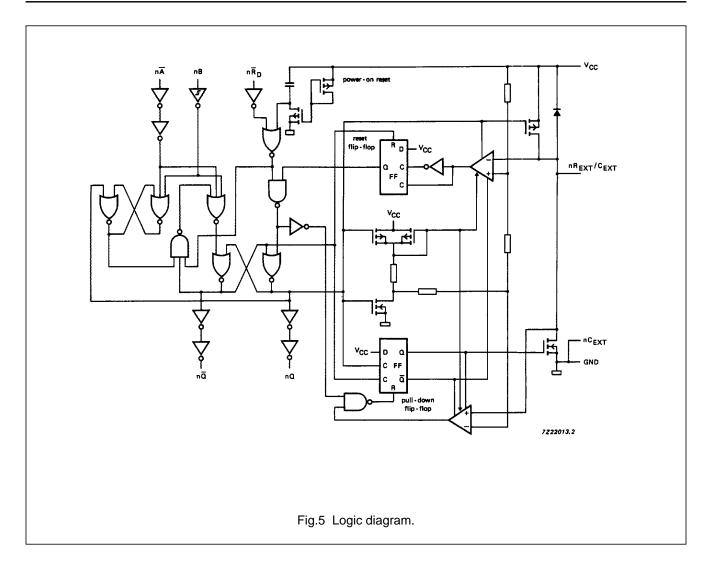
↓ = HIGH-to-LOW level

= one HIGH-level output pulse = one LOW-level output pulse

2. If the monostable was triggered before this condition was established the pulse will continue as programmed.

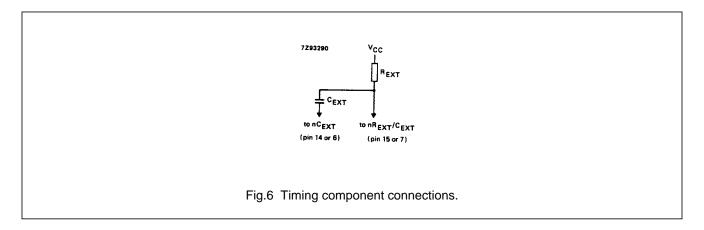
3. For this combination the reset input must be LOW and the following sequence must be used: pin 1 (or 9) must be set HIGH or pin 2 (or 10) set LOW; then pin 1 (or 9) must be LOW and pin 2 (or 10) set HIGH. Now the reset input goes from LOW-to-HIGH and the device will be triggered.

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### Note

It is recommended to ground pins 6 ( $2C_{EXT}$ ) and 14 ( $1C_{EXT}$ ) externally to pin 8 (GND).



# Dual non-retriggerable monostable multivibrator with reset

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#### DC CHARACTERISTICS FOR 74HC

For the DC characteristics see "74HC/HCT/HCU/HCMOS Logic Family Specifications".

Output capability: standard (except for  $nR_{EXT}/C_{EXT}$ )

I<sub>CC</sub> category: MSI

#### **AC CHARACTERISTICS FOR 74HC**

 $GND = 0 V; t_r = t_f = 6 ns; C_L = 50 pF$ 

					T <sub>amb</sub> (		TES	TEST CONDITIONS			
0.415.01					74H						
SYMBOL	PARAMETER	+25			-40 to +85		-40 to +125		UNIT	V <sub>CC</sub>	WAVEFORMS
		min	typ	max.	min	max.	min.	max.		(',	
t <sub>PLH</sub>	propagation delay (trigger) nĀ, nB to nQ		72 26 21	220 44 37		275 55 47		330 66 56	ns	2.0 4.5 6.0	$C_{EXT} = 0 \text{ pF};$ $R_{EXT} = 5 \text{ k}\Omega;$ Fig.10
t <sub>PLH</sub>	propagation delay (trigger) nR <sub>D</sub> to nQ		80 29 23	245 49 42		305 61 52		370 74 63	ns	2.0 4.5 6.0	$C_{EXT} = 0 \text{ pF};$ $R_{EXT} = 5 \text{ k}\Omega;$ Fig.10
t <sub>PHL</sub>	propagation delay (trigger) nĀ, nB to nQ		58 21 17	180 36 31		225 45 38		270 54 46	ns	2.0 4.5 6.0	$C_{EXT}$ = 0 pF; $R_{EXT}$ = 5 k $\Omega$ ; Fig.10
t <sub>PHL</sub>	propagation delay (trigger) $n\overline{R}_D$ to $n\overline{Q}$		63 23 18	195 39 33		245 49 42		295 59 50	ns	2.0 4.5 6,0	$C_{EXT}$ = 0 pF; $R_{EXT}$ = 5 k $\Omega$ ; Fig.10
t <sub>PLH</sub>	$\begin{array}{c} \text{propagation delay (reset)} \\ \text{n$\overline{R}_D$ to n$\overline{Q}$} \end{array}$		66 24 19	200 40 34		250 50 43		300 60 51	ns	2.0 4.5 6.0	$C_{EXT} = 0 \text{ pF};$ $R_{EXT} = 5 \text{ k}\Omega;$ Fig.11
t <sub>PLH</sub>	propagation delay (reset) nR <sub>D</sub> to nQ		58 21 17	180 36 31		225 45 38		270 54 46	ns	2.0 4.5 6.0	$C_{EXT}$ = 0 pF; $R_{EXT}$ = 5 k $\Omega$ ; Fig.11
t <sub>THL</sub> / t <sub>TLH</sub>	output transition time		19 7 6	75 15 13		95 19 16		110 22 19	ns	2.0 4.5 6.0	Fig.10
t <sub>W</sub>	trigger pulse width nA = LOW	75 15 13	25 9 7		95 19 16		110 22 19		ns	2.0 4.5 6.0	Fig.7
t <sub>W</sub>	trigger pulse width nB = HIGH	90 18 15	30 11 9		115 23 20		135 27 23		ns	2.0 4.5 6.0	Fig.7
t <sub>W</sub>	trigger pulse width $n\overline{R}_D = LOW$	75 15 13	25 9 7		95 19 16		110 22 19		ns	2.0 4.5 6.0	Fig.8
t <sub>W</sub>	output pulse width $n\overline{Q} = LOW$ $nQ = HIGH$	630	700	770	602	798	595	805	μs	5.0	$C_{EXT}$ = 100 nF; $R_{EXT}$ = 10 k $\Omega$ ; Fig.10

# Dual non-retriggerable monostable multivibrator with reset

	PARAMETER			•	T <sub>amb</sub> (		TEST CONDITIONS				
CVMDOL					74H	UNIT		WAVEFORMS			
SYMBOL	PARAMETER		+25		-40 to +85		-40 to +125		UNIT	V <sub>CC</sub>	WAVEFORWS
		min	typ	max.	min	max.	min.	max.		(-,	
t <sub>W</sub>	output pulse width nQ or nQ		140		_		_		ns	2.0 4.5 6.0	$C_{EXT}$ = 28 nF; $R_{EXT}$ = 2 k $\Omega$ ; Fig.10
t <sub>W</sub>	output pulse width nQ or nQ		1.5		_		_		μs	2.0 4.5 6.0	$C_{EXT}$ = 1 nF; $R_{EXT}$ = 2 k $\Omega$ ; Fig.10
t <sub>W</sub>	output pulse width nQ or nQ		7		_		_		μs	2.0 4.5 6.0	$C_{EXT}$ = 1 nF; $R_{EXT}$ = 10 k $\Omega$ ; Fig.10
t <sub>W</sub>	pulse width match between circuits in the package		± 2		_		_		%	4.5 to 5.5	$C_{EXT} = 1000 \text{ pF};$ $R_{EXT} = 10 \text{ k}\Omega$
t <sub>rem</sub>	removal time nR <sub>D</sub> to nA or nB	100 20 17	30 11 9		125 25 21		150 30 26		ns	2.0 4.5 6.0	Fig.9
R <sub>EXT</sub>	external timing resistor	10 2		1000 1000	_				kΩ	2.0 5.0	Fig.12 Fig.13
C <sub>EXT</sub>	external timing capacitor	no lin	nits						pF	2.0 5.0	Fig.12 Fig.13

# Dual non-retriggerable monostable multivibrator with reset

74HC/HCT221

#### DC CHARACTERISTICS FOR 74HCT

For the DC characteristics see "74HC/HCT/HCU/HCMOS Logic Family Specifications".

Output capability: standard (except for nR<sub>EXT</sub>/C<sub>EXT</sub>)

I<sub>CC</sub> category: MSI

#### Note to HCT types

The value of additional quiescent supply current ( $\Delta I_{CC}$ ) for a unit load of 1 is given in the family specifications. To determine  $\Delta I_{CC}$  per input, multiply this value by the unit load coefficient shown in the table below.

INPUT	UNIT LOAD COEFFICIENT
nB	0.30
nĀ	0.50
$n\overline{R}_D$	0.50

# Dual non-retriggerable monostable multivibrator with reset

### 74HC/HCT221

### **AC CHARACTERISTICS FOR 74HCT**

 $GND = 0 V; t_r = t_f = 6 ns; C_L = 50 pF$ 

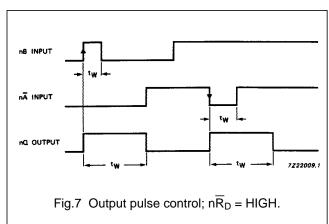
		T <sub>amb</sub> (°C)								TEST CONDITIONS		
0.44501	PARAMETER				74H	СТ	UNIT					
SYMBOL		+25		-40 to +85   -40		-40 to	-40 to +125		V <sub>CC</sub>	WAVEFORMS		
		min	typ	max	min	max.	min.	max.		(•)		
t <sub>PLH</sub>	propagation delay (trigger) nĀ, nR̄ <sub>D</sub> to nQ		30	50		63		75	ns	4.5	$C_{EXT}$ = 0 pF; $R_{EXT}$ = 5 k $\Omega$ ; Fig.10	
t <sub>PLH</sub>	propagation delay (trigger) nB to nQ		24	42		53		63	ns	4.5	$C_{EXT} = 0 \text{ pF};$ $R_{EXT} = 5 \text{ k}\Omega;$ Fig.10	
t <sub>PHL</sub>	propagation delay (trigger) nĀ to nQ		26	44		55		66	ns	4.5	$C_{EXT} = 0 \text{ pF};$ $R_{EXT} = 5 \text{ k}\Omega;$ Fig.10	
t <sub>PHL</sub>	propagation delay (trigger) nB to nQ		21	35		44		53	ns	4.5	$C_{EXT} = 0 \text{ pF};$ $R_{EXT} = 5 \text{ k}\Omega;$ Fig.10	
t <sub>PHL</sub>	propagation delay (trigger) nR <sub>D</sub> to nQ		26	43		54		65	ns	4.5	$C_{EXT} = 0 \text{ pF};$ $R_{EXT} = 5 \text{ k}\Omega;$ Fig.10	
t <sub>PHL</sub>	propagation delay (reset) nR <sub>D</sub> to nQ		26	43		54		65	ns	4.5	$C_{EXT} = 0 \text{ pF};$ $R_{EXT} = 5 \text{ k}\Omega;$ Fig.11	
t <sub>PLH</sub>	$\begin{array}{c} \text{propagation delay (reset)} \\ \text{n$\overline{R}_D$ to n$\overline{Q}$} \end{array}$		31	51		64		77	ns	4.5	$C_{EXT} = 0 \text{ pF};$ $R_{EXT} = 5 \text{ k}\Omega;$ Fig.11	
t <sub>THL</sub> / t <sub>TLH</sub>	output transition time		7	15		19		22	ns	4.5	Fig.10	
t <sub>W</sub>	trigger pulse width nA = LOW	20	13		25		30		ns	4.5	Fig.10	
t <sub>W</sub>	trigger pulse width nB = HIGH	20	13		25		30		ns	4.5	Fig.10	
t <sub>W</sub>	pulse width nRD = LOW	22	13		28		33		ns	4.5	Fig.8	
t <sub>W</sub>	output pulse width  nQ = LOW  nQ = HIGH	630	700	770	602	798	595	805	μs	5.0	$C_{EXT}$ = 100 nF; $R_{EXT}$ = 10 k $\Omega$ ; Fig.10	
t <sub>W</sub>	trigger pulse width nQ or nQ		140		_		_		ns	4.5	$C_{EXT}$ = 28 pF; $R_{EXT}$ = 2 k $\Omega$ ; Fig.10	
t <sub>W</sub>	trigger pulse width nQ or nQ		1.5		_		_		μs	4.5	$C_{EXT} = 1 \text{ nF};$ $R_{EXT} = 2 \text{ k}\Omega;$ Fig.10	

# Dual non-retriggerable monostable multivibrator with reset

	PARAMETER	T <sub>amb</sub> (°C)								TEST CONDITIONS		
SYMBOL					74H	] 		WAVEFORMO				
STIVIBUL		+25			-40 to +85		-40 to +125		UNIT	V <sub>CC</sub> (V)	WAVEFORMS	
		min	typ	max	min	max.	min.	max.		(*)		
t <sub>W</sub>	trigger pulse width nQ or nQ		7		_		_		μs	4.5	$C_{EXT}$ = 1 nF; $R_{EXT}$ = 10 k $\Omega$ ; Fig.10	
t <sub>rem</sub>	removal time nR <sub>D</sub> to nA or nB	20	12		25		30		ns	4.5	Fig.9	
R <sub>EXT</sub>	external timing resistor	2		1000	_		_		kΩ	5.0	Fig.13	
C <sub>EXT</sub>	external timing capacitor	no limits							pF	5.0	Fig.13	

### 74HC/HCT221

#### **AC WAVEFORMS**



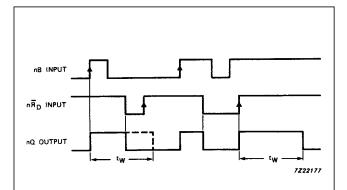
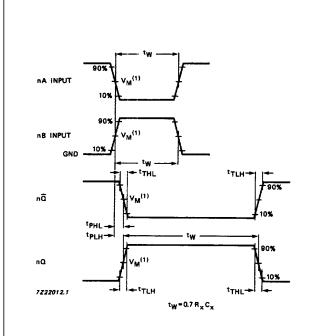
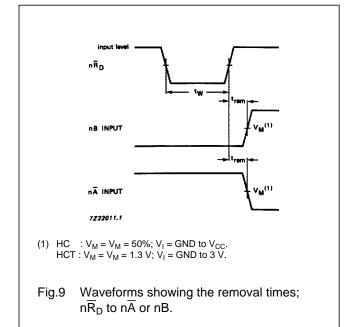


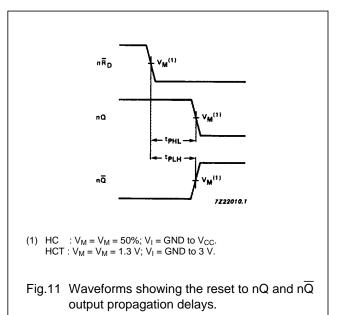
Fig.8 Output pulse control using reset input  $n\overline{R}_D$ ;  $n\overline{A} = LOW$ .

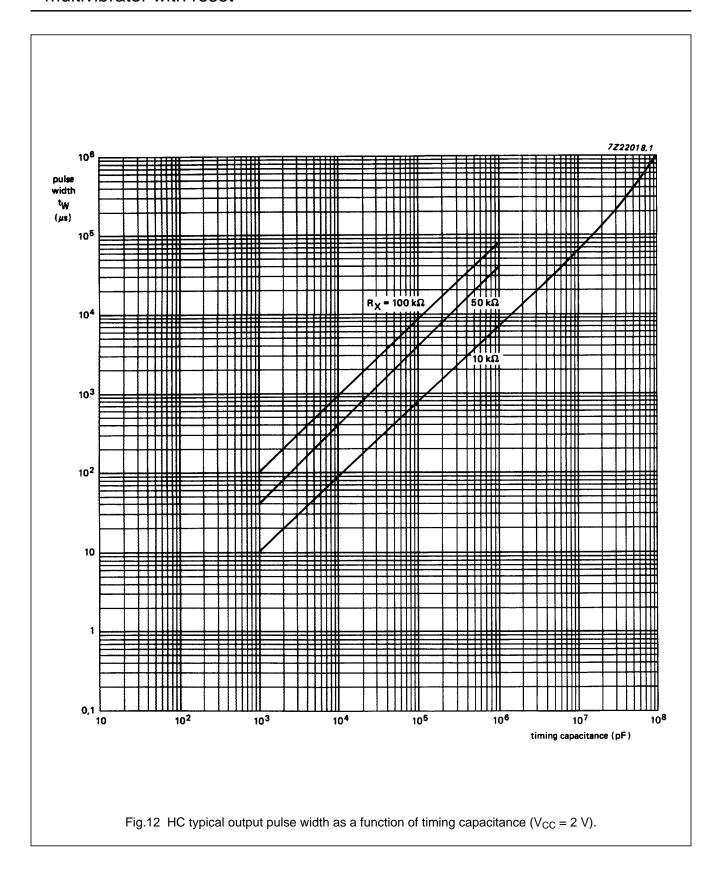


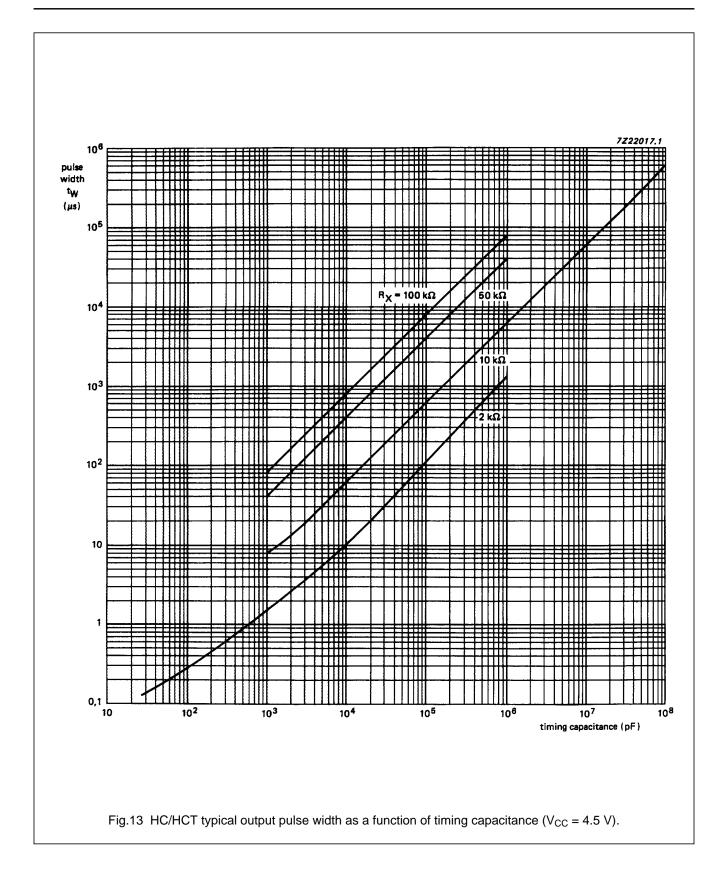
(1) HC :  $V_M = V_M = 50\%$ ;  $V_I = GND$  to  $V_{CC}$ . HCT :  $V_M = V_M = 1.3$  V;  $V_I = GND$  to 3 V.

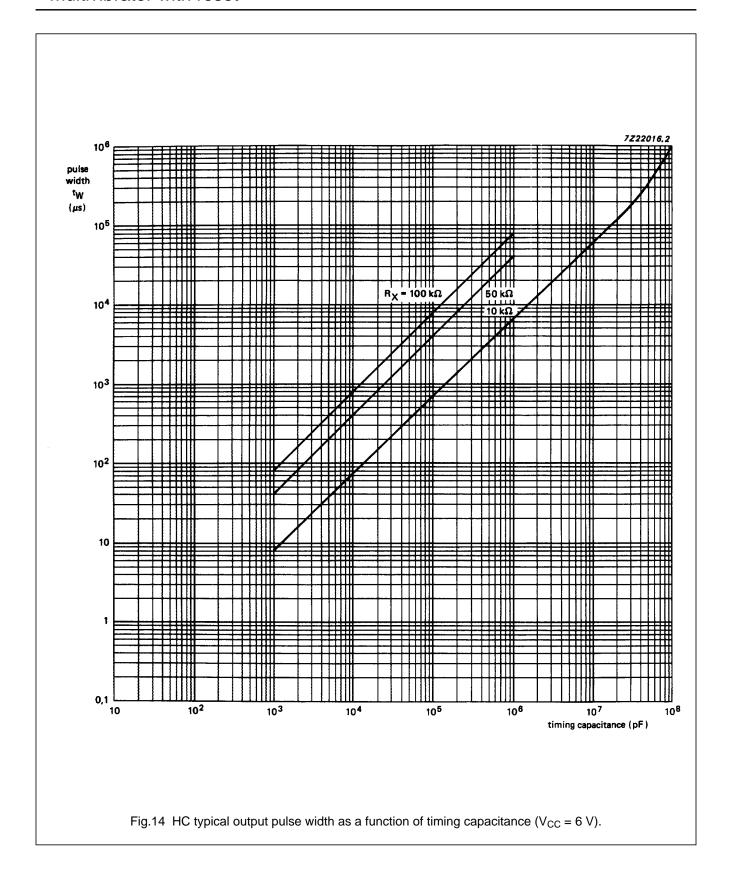
Fig.10 Waveforms showing the triggering of One Shot by input  $n\overline{A}$  or input nB for one period  $(t_W)$  and minimum pulse widths of the trigger inputs  $n\overline{A}$  and nB.











# Dual non-retriggerable monostable multivibrator with reset

### 74HC/HCT221

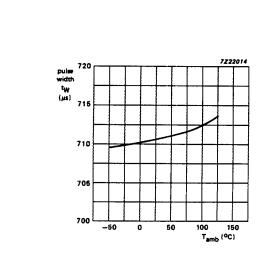
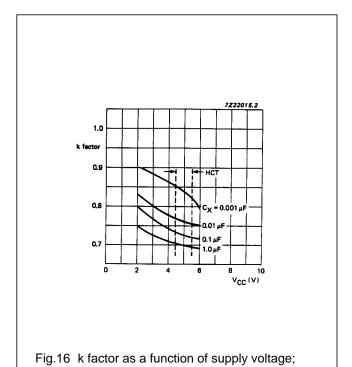


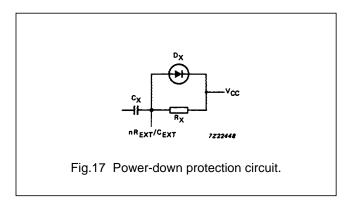
Fig.15 Typical output pulse width as a function of temperature;  $C_X$  = 0.1  $\mu F$ ;  $R_X$  = 10  $K\Omega$ ;  $V_{CC}$  = 5 V.



 $R_X = 10 \text{ K}\Omega$ ;  $T_{amb} = 25 \text{ °C}$ .

#### **Power-down consideration**

A large capacitor  $(C_X)$  may cause problems when powering-down the monostable due to the energy stored in this capacitor. When a system containing this device is powered-down or a rapid decrease of  $V_{CC}$  to zero occurs, the monostable may substain damage, due to the capacitor discharging through the input protection diodes. To avoid this possibility, use a damping diode  $(D_X)$  preferably a germanium or Schottky type diode able to withstand large current surges and connect as shown in Fig.17.



#### **PACKAGE OUTLINES**

See "74HC/HCT/HCU/HCMOS Logic Package Outlines".